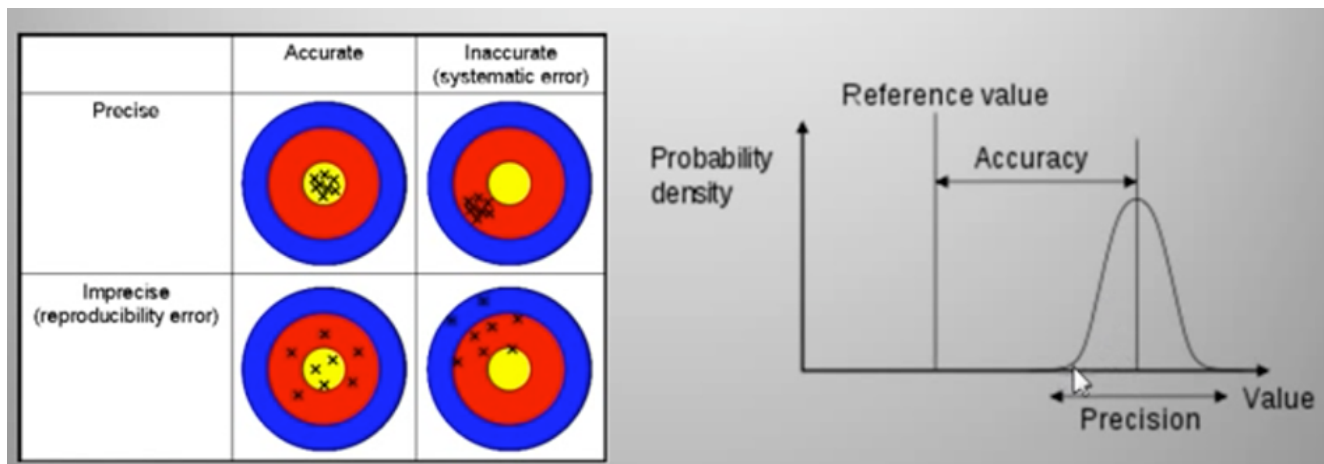


## Key Terms



### 1) Precision

a measure of the certainty ( $\pm$ ), that is how close each measurement is to each other  
E.g., height =  $182.23 \pm 0.01$  cm

### 2) Accuracy

how close the measured value is to the true or accepted value

### 3) Random Error

an error in measurement caused by factors that vary from one measurement to another, usually due to limitations of equipment - can be minimized by averaging multiple trials

### 4) Systematic Error

an error having a nonzero mean, so that its effect is not reduced when observations are averaged, usually due to instrument or method error

## Measuring Device Uncertainty

Always report uncertainty to 1 or 2 significant figures

### 1) Analog Measuring Device

for each end of a ruler =  $\pm \frac{1}{2}$  (the smallest scale division)

### 2) Digital Device

1) Look in the equipment manual to determine the device resolution for a given setting range

2) If you do not have a manual use  
 $\pm 1$  of the smallest unit displayed

### 3) Repeated Measurements

- 1) If repeated measurements yield different values for each measurement then  
 $\text{mean} \pm 1/2(\text{Max} - \text{Min})$  or  $\text{mean} \pm \text{std dev}$  (for roughly symmetric data sets)
- 2) If repeated measurements all yield the same value then  
 $\text{mean} \pm \text{resolution of the measuring device}$

### Uncertainty Propagation

#### 1) Addition and Subtraction

Length =  $L_1 + L_2$  where  $\delta L_1$  and  $\delta L_2$  are the uncertainties

##### 1) Worst Case Uncertainty

Add the absolute uncertainties

$$\text{Worst Case Uncertainty in Length} = \delta L = |\delta L_1| + |\delta L_2|$$

##### 2) Statistical Uncertainty

$$\text{Uncertainty in Length} = \delta L = \sqrt{(\delta L_1)^2 + (\delta L_2)^2}$$

#### 2) Multiplication and Division

Area =  $L * W$  where  $\delta L$  and  $\delta W$  are the uncertainties

##### 1) Worst Case Uncertainty

Add absolute fractional or percent fractional uncertainties

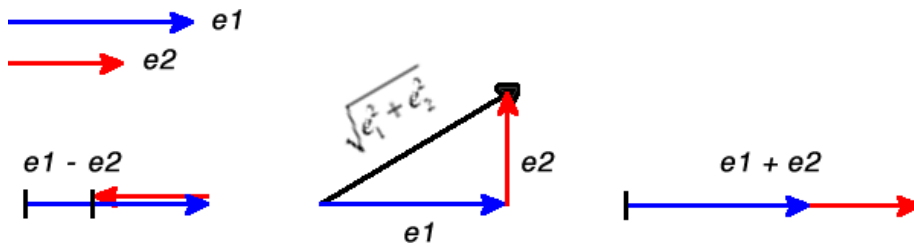
$$\text{Worst Case Fractional Uncertainty in Area} = \frac{\delta A}{A} = \left| \frac{\delta L}{L} \right| + \left| \frac{\delta W}{W} \right|$$

##### 2) Statistical Uncertainty

$$\text{Fractional Uncertainty in Area} = \frac{\delta A}{A} = \sqrt{\left( \frac{\delta L}{L} \right)^2 + \left( \frac{\delta W}{W} \right)^2}$$

### Uncertainty Propagation in Quadrature (statistical best estimate)

Length =  $L_1 + L_2$  where  $\pm e_1$  and  $\pm e_2$  are the uncertainties respectively



$$\begin{aligned}\sqrt{e_1^2 + e_2^2} &< e_1 + e_2 \\ &> e_1 \\ &> e_2\end{aligned}$$

#### 1) Uncertainty in a Function of Several Variables

**All measurement quantities must be independent and subject to only random uncertainties**

$$\delta f(x, y, z) = \sqrt{\left(\frac{\partial f}{\partial x} \delta x\right)^2 + \left(\frac{\partial f}{\partial y} \delta y\right)^2 + \left(\frac{\partial f}{\partial z} \delta z\right)^2} \quad \text{Statistical Uncertainty}$$

$$\delta f(x, y, z) \leq \left| \frac{\partial f}{\partial x} \delta x \right| + \left| \frac{\partial f}{\partial y} \delta y \right| + \left| \frac{\partial f}{\partial z} \delta z \right| \quad \text{Worst Case Uncertainty}$$

#### 2) Tricks and Shortcuts

##### 1) Multiplication by a Constant

$$f(x) = Cx \quad \text{where } C \text{ is a constant} \quad \Rightarrow \quad \delta f = \frac{\partial f}{\partial x} \delta x = C \delta x$$

When multiplying your  $f$  measurement by a constant, multiply its uncertainty by the same constant

If measured  $x = 5.614 \pm 0.006$

then 10 times  $x = 56.14 \pm 0.06$

##### 2) Addition and Subtraction

$$f(x, y) = \pm x \pm y \Rightarrow \delta f = \sqrt{\left(\frac{\partial f}{\partial x} \delta x\right)^2 + \left(\frac{\partial f}{\partial y} \delta y\right)^2} = \sqrt{(\delta x)^2 + (\delta y)^2}$$

##### 3) Multiplication and Division

$$f(x, y) = xy \Rightarrow \delta f = \sqrt{\left(\frac{\partial f}{\partial x} \delta x\right)^2 + \left(\frac{\partial f}{\partial y} \delta y\right)^2} = \sqrt{(y \delta x)^2 + (x \delta y)^2} \Rightarrow \frac{\delta f}{f} = \sqrt{\left(\frac{\delta x}{x}\right)^2 + \left(\frac{\delta y}{y}\right)^2}$$

The relative or fractional uncertainties add in quadrature.

## 4) Powers

$$f(x) = x^n \Rightarrow \delta f = \sqrt{\left(\frac{\partial f}{\partial x} \delta x\right)^2} = \sqrt{(nx^{n-1} \delta x)^2} \Rightarrow \frac{\delta f}{f} = \sqrt{\left(\frac{n \delta x}{x}\right)^2} = \left|\frac{n \delta x}{x}\right|$$

## 3) Example: Kinetic Energy

mass =  $10.12 \pm 0.11 \text{kg}$  and velocity =  $2.34 \pm 0.04 \text{m/s}$

$$K(v) = \frac{1}{2}mv^2 \Rightarrow \delta K = \sqrt{\left(\frac{\partial K}{\partial m} \delta m\right)^2 + \left(\frac{\partial K}{\partial v} \delta v\right)^2} = \sqrt{\left(\frac{1}{2}v^2 \delta m\right)^2 + (mv \delta v)^2}$$

$$\delta K = \sqrt{\left(\frac{1}{2}(2.34 \text{m/s})^2(0.11 \text{kg})\right)^2 + ((10.12 \text{kg})(2.34 \text{m/s})(0.04 \text{m/s}))^2} = 0.9939540 \text{J} \Rightarrow 0.99 \text{J}$$

**Scatter Plot with Error Bars**

## 1) Best Fit Straight Line (Linear Regression)

## 1) Max and Min gradient (slope) lines

Use endpoints and error on each end to fit line for max and min slope of line